

Servo amplifier

mcDSA-E47

Article number: 1511153

**Technical data**

Absolute maximum rating (destruction limits)		Sensor supply (Encoder)
Power supply voltage Up no polarity reversal protection	80 V	Output voltage 5 V
Continuous Electronic supply voltage Ue no polarity reversal protection	33 V	Max. output current 0.2 A
Short term peak voltage < 1s Ue no polarity reversal protection	37 V	Encoder
Power		Type sin / cos
Electronic supply voltage Ue	9..30 V	Signals +Sin,-Sin,+Cos,-Cos
Electronic current consumption@ Ue=24V*1	typ. 60 mA	Resolution 13 bit per sine period
Power supply voltage Up	9..60 V	Input voltage 1 V peak-peak, differential
Max. output current	50 A	Signal type sine/cosine, analog, differential
Continuous output current @ Up=24V*2	10 A	Digital inputs
Continuous output current @ Up=48V*2	8.5 A	Number - digital inputs 7 (Din0..6)
PWM		Low voltage 0.5 V
Output voltage	100% Up	High voltage 8..30 V
PWM frequency	25, 32*3, 50 kHz	Digital outputs
Mechanical		Number 2 (Dout0..1)
Size LxWxH	110 x 22.5 x 77 mm	Continuous output current 1.5 A
Weight	110 g	Load resistive, inductive
Environment		Output voltage Electronic supply voltage Ue
Protection class	IP20	Signal type positive switching
Ambient temperature (operation)*4	-40..70 °C	Analog inputs
Ambient temperature (storage)	-40..85 °C	Number 2 (Ain0..1)
Rel. humidity (non-condensing)	5..90 %	Signal type - Ain0 +/- 10 V, 12 Bit, differential
CAN bus		Signal type - Ain1 +/- 10 V, 12 Bit, single ended
Protocol	DS301	
Device profile	DS402	
Max. baudrate	1 Mbit/s	
CAN specification	2.0B	
Galvanically isolated	no	

*1 power amplifier switched off, 5V output (sensor supply) is free

*2 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C (t >40 °C derating), RMS current: 10 A → 8.2 Aeff, 8.5 A → 6.9 Aeff

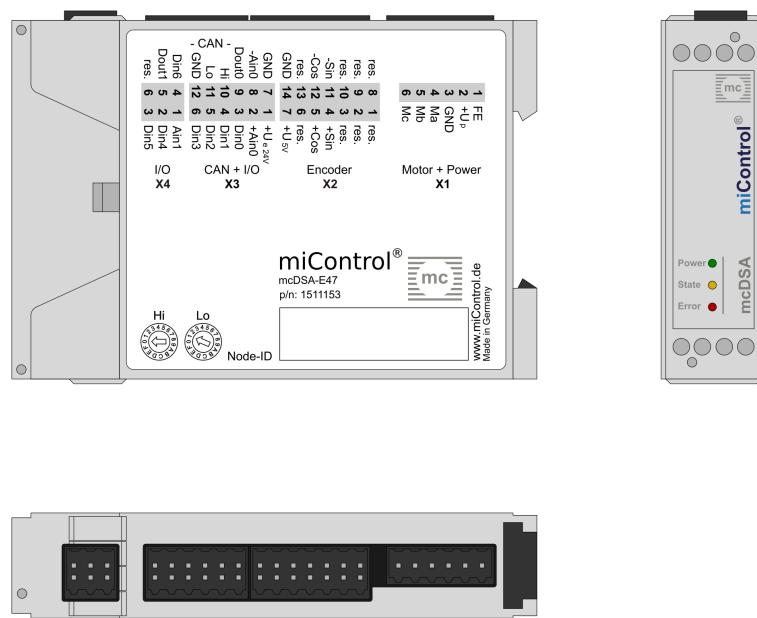
no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*3 default value

*4 Hex-Switches should be not used at T < -25°C (setting of node ID only possible by firmware parameters)

Additional technical data are available in mcManual.

Scheme



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Terminal assignment

X1	Motor	
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	Ma	Motor phase A
5	Mb	Motor phase B
6	Mc	Motor phase C
X2	Encoder	
1	res.	Reserved
2	res.	Reserved
3	res.	Reserved
4	+Sin	Encoder, plus sine signal
5	+Cos	Encoder, plus cosine signal
6	res.	Reserved
7	+U5V	5V output voltage for sensor supply Sensors: encoder
8	res.	Reserved
9	res.	Reserved
10	res.	Reserved
11	-Sin	Encoder, minus sine signal
12	-Cos	Encoder, minus cosine signal
13	res.	Reserved
14	GND	Ground for sensor supply Notice: don't connect with system GND
X3	I/O's and CAN	
1	+Ue24V	Electronic supply voltage
2	+Ain0	Analog input 0, plus
3	Din0	Digital input 0
4	Din1	Digital input 1
5	Din2	Digital input 2
6	Din3	Digital input 3
7	GND	Ground for electronic supply voltage
8	-Ain0	Analog input 0, minus
9	Dout0	Digital output 0
10	CAN Hi	CAN High
11	CAN Lo	CAN Low
12	CAN GND	CAN Ground

X4	I/O's
1	Ain1
2	Din4
3	Din5
4	Din6
5	Dout1
6	res.