

Servo amplifier

mcDSA-E40-Lp

Article number: 1513022

Certification:  *1
E475093



Picture similar

Technical data

Absolute maximum rating (destruction limits)		Sensor supply (Encoder/Hall)
Power supply voltage Up no polarity reversal protection	80 V	Output voltage 5 V
Continuous Electronic supply voltage Ue no polarity reversal protection	33 V	Max. output current 0.2 A
Short term peak voltage < 1s Ue no polarity reversal protection	37 V	Incremental encoder
Power		Type incremental
Electronic supply voltage Ue	9..30 V	Signals A,/A,B,/B,I _{nx} ,I _{nx}
Electronic current consumption@ Ue=24V*2	typ. 50 mA	Max. frequency (per channel) 500 kHz
Power supply voltage Up	9..60 V	Input voltage (24V tolerant) 0.5 V
Max. output current	30 A	Signal type differential, open collector, single ended
Continuous output current @ Up=24V*3	10 A	Hall sensors
Continuous output current @ Up=48V*3	8.5 A	Signals H1,/H1,H2,/H2,H3,/H3
Continuous output current (certified UL)*4 @Up=24V	10 A	Max. frequency (per channel) 10 kHz
@Up=60V	8 A	Input voltage (24V tolerant) 0.5 V
PWM		Signal type differential, open collector, single ended
Output voltage	90% Up	Digital inputs
PWM frequency	25, 32*5, 50 kHz	Number - digital inputs 4 (Din0..3)
Mechanical		Low voltage 0.5 V
Size LxWxH	97.5 x 71 x 13 mm	High voltage 8..30 V
Weight	58 g	Digital outputs
Environment		Number 1 (Dout0)
Protection class	IP00	Continuous output current (certified UL) 0.75 A
Ambient temperature (operation) (certified UL)*6	-40..40 °C	Continuous output current (not certified) 1.5 A
Ambient temperature (operation) (not certified)*6	-40..70 °C	Load resistive, inductive
Ambient temperature (storage)	-40..85 °C	Output voltage Electronic supply voltage Ue
Rel. humidity (non-condensing)	5..90 %	Signal type positive switching
CAN bus		Analog inputs
Protocol	DS301	Number 1 (Ain0)
Device profile	DS402	Signal type 0..10 V, 12 Bit, single ended
Max. baudrate	1 Mbit/s	
CAN specification	2.0B	
Galvanically isolated	no	

*1 The certified performance data must be observed (see UL Instruction Note)

*2 power amplifier switched off, 5V output (sensor supply) is free

*3 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C (t >40 °C derating), RMS current: 10 A → 8.2 Aeff, 8.5 A → 6.9 Aeff

no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*4 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C, I/O's and 5V output active, RMS current: 10 A → 8.2 Aeff, 8 A → 6.5 Aeff

*5 default value

*6 Hex-Switches should be not used at T < -25°C (setting of node ID only possible by firmware parameters)

Additional technical data are available in mcManual.



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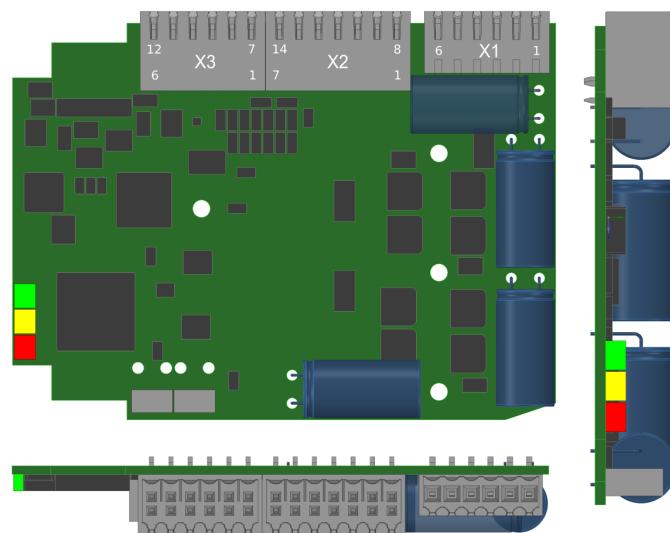
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Scheme



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Terminal assignment

X1 Motor		
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	Ma	Motor phase A
5	Mb	Motor phase B
6	Mc	Motor phase C
X2 Hall and inc. encoder		
1	H1	Hall sensor 1
2	H2	Hall sensor 2
3	H3	Hall sensor 3
4	A	Inc. encoder, A channel
5	B	Inc. encoder, B channel
6	Inx	Inc. encoder, index channel
7	+U5V	5V output voltage for sensor supply Sensors: encoder, hall
8	/H1	Hall sensor 1 inverted
9	/H2	Hall sensor 2 inverted
10	/H3	Hall sensor 3 inverted
11	/A	Inc. encoder, A channel inverted
12	/B	Inc. encoder, B channel inverted
13	/Inx	Inc. encoder, index channel inverted
14	GND	Ground for sensor supply Notice: don't connect with system GND
X3 I/O's and CAN		
1	+Ue24V	Electronic supply voltage
2	Ain0	Analog input 0
3	Din0	Digital input 0
4	Din1	Digital input 1
5	Din2	Digital input 2
6	Din3	Digital input 3
7	GND	Ground for electronic supply voltage
8	res.	Reserved
9	Dout0	Digital output 0
10	CAN Hi	CAN High
11	CAN Lo	CAN Low
12	CAN GND	CAN Ground